



# Application Note

## AN\_350

# FT800\_on\_Raspberry\_Pi

**Version 1.1**

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This application note demonstrates a way of interfacing the FT800 to a Raspberry Pi. The FT800 is connected to the USB port of the Raspberry Pi via an MPSSE interface. An application running on the Raspberry Pi communicates with the FT800 through the FTDI Linux D2xx driver. This application note provides a simple example of developing C code to control the FT800, and the principles demonstrated can then be used to produce more complex applications

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## 1 Introduction

This application note documents how to connect a small display to a single board computer (SBC). It uses a Raspberry Pi (RPI) as the SBC and a VM800BU as the FT800 driven small display module. The VM800BU was chosen specifically as it has a USB interface, thus freeing up the RPI SPI ports for other functions.

Project source code may be [downloaded from this link](#).

The sample project can work for any SBC with Linux OS and VM800BU and will 4 colored circles as shown in section 5 to demonstrate the connectivity.

### 1.1 Scope

This application can be used for most kinds of SBC with a USB host port and is not limited to the Raspberry Pi. However, the Raspberry Pi was chosen for this demonstration due to the widely available hardware platform and OS images.

This document describes how to connect and run an FT800 demo program on a Raspberry Pi system. Creating and configuring a Raspberry Pi board image is beyond the scope of this application note.

### 1.2 Software Required

This sample application requires the following software resources:

- Raspberry PIDORA (users may use other Linux OS for their systems)
- FTDI Linux D2XX driver for ARM processors (version 1.1.12 or later). Available from the [FTDI drivers page](#)

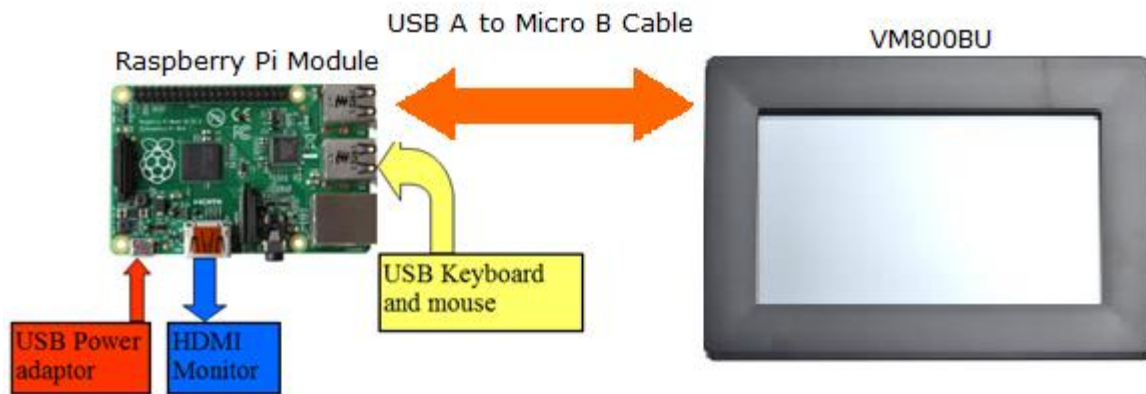
### 1.3 Hardware Required

- Raspberry Pi B+ board (or other SBC systems) with a TF card (4G bytes or more)
- VM800BU module (see note)
- USB A to Micro B cable (suggest FTDI accessory VA-FC-1M-BKW or VA-FC-1M-BLW)

Note: The VM800BU already includes an on-board USB-SPI interface and is recommended. However a VM800B or VM800C may be connected via an additional USB to SPI bridge such as the C232HM DDHSL-0 cable or VA800A-SPI module or directly to the RPI SPI port.

## 2 Hardware Block Diagram and Connection

This section summarizes the hardware connections used. A VM800BU is shown connected via the USB A to Micro B cable.



**Figure 2.1 Hardware Block Diagram**

## 3 Software

### 3.1 Software Layer Diagram

The software consists of several different layers, as shown below. The SampleApp.c file is where the actual FT800 application would be created. Users should modify the SampleApp.c file to create different displays. All the Co-processor Engine commands are provided in the project. Refer to [Section 3.3](#) FT\_CoPro\_Cmds.h for more detail information.

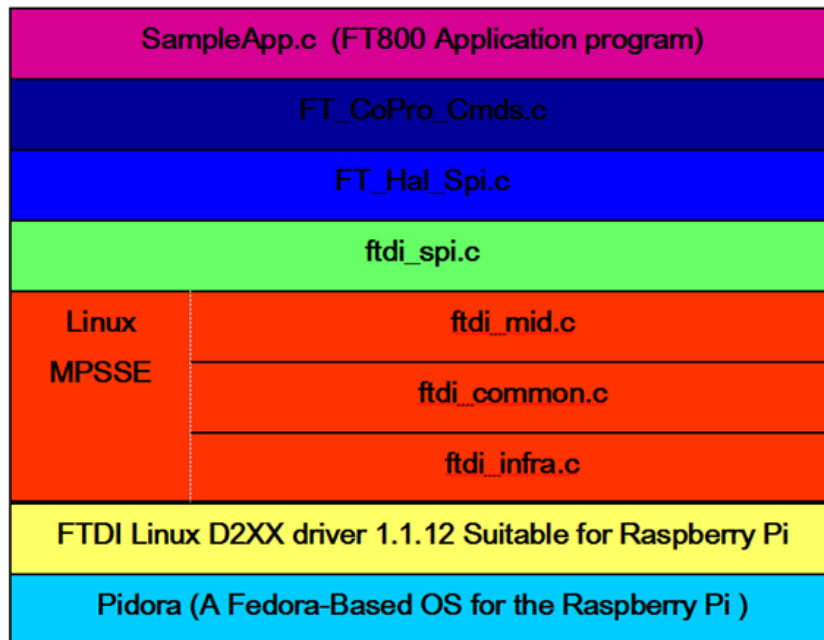


Figure 3.1 Software Layer Diagram

### 3.2 Sample code (main program is in SampleApp.c)

The syntax of the sample code is very similar to the [FT800 Programmers Guide](#). Please refer to the following figure for more detail. This is based on the code shown in section 2.5.3 of the [FT800 Programmers Guide](#). Figure 3.2 shows how to draw points with varying radius from 5 pixels to 13 pixels with different colors.

```

hal_gpu_dl(CLEAR(1,1,1)); // Clear the screen
hal_gpu_dl(COLOR_RGB(128, 0, 0) ); // Set the draw color to Red
hal_gpu_dl(POINT_SIZE(5 * 16) ); // Set size to 5 * 16 /16 = 5 pixels
hal_gpu_dl(BEGIN(FTPPOINTS) ); // Start the point draw
hal_gpu_dl(VERTEX2F(30 * 16, 17 * 16) ); // Draw circle 30 pixels from left and 17 down
hal_gpu_dl(COLOR_RGB(0, 128, 0) ); // Set the draw color to Green
hal_gpu_dl(POINT_SIZE(8 * 16) ); // Set size to 8 * 16 /16 = 8 pixels
hal_gpu_dl(VERTEX2F(90 * 16, 17 * 16) ); // Draw circle 90 pixels from left and 17 down
hal_gpu_dl(COLOR_RGB(0, 0, 128) ); // Set the draw color to Blue
hal_gpu_dl(POINT_SIZE(10 * 16) ); // Set size to 10 * 16 /16 = 10 pixels
hal_gpu_dl(VERTEX2F(30 * 16, 51 * 16) ); // Draw circle 30 pixels from left and 51 down
hal_gpu_dl(COLOR_RGB(128, 128, 0) ); // Set the draw color to Yellow
hal_gpu_dl(POINT_SIZE(13 * 16) ); // Set size to 13 * 16 /16 = 13 pixels
hal_gpu_dl(VERTEX2F(90 * 16, 51 * 16) ); // Draw circle 90 pixels from left and 51 down
hal_gpu_dl(DISPLAY()); // End the display list
hal_spi_wr8(REG_DLSWAP,DLSWAP_FRAME); // Make this display list active on the next frame

```

Figure 3.2 The real drawing commands of the Sample Code

### 3.3 FT\_CoPro\_Cmds.h

All available Co-Processor Engine commands are defined in FT\_CoPro\_Cmds.h

```
ft_void hal_spi_cmd_text(ft_int16_t x, ft_int16_t y, ft_int16_t font, ft_uint16_t options, const ft_char8_t* s);
ft_void hal_spi_cmd_number(ft_int16_t x, ft_int16_t y, ft_int16_t font, ft_uint16_t options, ft_int32_t n);
ft_void hal_spi_cmd_loadidentity();
ft_void hal_spi_cmd_toggle(ft_int16_t x, ft_int16_t y, ft_int16_t w, ft_int16_t font, ft_uint16_t options, ft_uint16_t state, const ft_char8_t* s);
ft_void hal_spi_cmd_gauge(ft_int16_t x, ft_int16_t y, ft_int16_t r, ft_uint16_t options, ft_uint16_t major, ft_uint16_t minor, ft_uint16_t val, ft_uint16_t range);
ft_void hal_spi_cmd_regread(ft_uint32_t ptr, ft_uint32_t result);
ft_void hal_spi_cmd_getprops(ft_uint32_t ptr, ft_uint32_t w, ft_uint32_t h);
ft_void hal_spi_cmd_memcpy(ft_uint32_t dest, ft_uint32_t src, ft_uint32_t num);
ft_void hal_spi_cmd_spinner(ft_int16_t x, ft_int16_t y, ft_uint16_t style, ft_uint16_t scale);
ft_void hal_spi_cmd_bgcolor(ft_uint32_t c);
ft_void hal_spi_cmd_swap();
ft_void hal_spi_cmd_inflate(ft_uint32_t ptr);
ft_void hal_spi_cmd_translate(ft_int32_t tx, ft_int32_t ty);
ft_void hal_spi_cmd_stop();
ft_void hal_spi_cmd_slider(ft_int16_t x, ft_int16_t y, ft_int16_t w, ft_int16_t h, ft_uint16_t options, ft_uint16_t val, ft_uint16_t range);
ft_void hal_spi_cmd_interrupt(ft_uint32_t ms);
ft_void hal_spi_cmd_fgcolor(ft_uint32_t c);
ft_void hal_spi_cmd_rotate(ft_int32_t a);
ft_void hal_spi_cmd_button(ft_int16_t x, ft_int16_t y, ft_int16_t w, ft_int16_t h, ft_int16_t font, ft_uint16_t options, const ft_char8_t* s);
ft_void hal_spi_cmd_memwrite(ft_uint32_t ptr, ft_uint32_t num);
ft_void hal_spi_cmd_scrollbar(ft_int16_t x, ft_int16_t y, ft_int16_t w, ft_int16_t h, ft_uint16_t options, ft_uint16_t val, ft_uint16_t size, ft_uint16_t range);
ft_void hal_spi_cmd_getmatrix(ft_int32_t a, ft_int32_t b, ft_int32_t c, ft_int32_t d, ft_int32_t e, ft_int32_t f);
ft_void hal_spi_cmd_sketch(ft_int16_t x, ft_int16_t y, ft_uint16_t w, ft_uint16_t h, ft_uint32_t ptr, ft_uint16_t format);
ft_void hal_spi_cmd_memset(ft_uint32_t ptr, ft_uint32_t value, ft_uint32_t num);
ft_void hal_spi_cmd_calibrate(ft_uint32_t result);
ft_void hal_spi_cmd_setfont(ft_uint32_t font, ft_uint32_t ptr);
```

**Figure 3.3 Parts of Co-Processor Engine commands**

## 4 Running the Example

In order to run the example, the FTDI D2xx driver must first be installed. Then, the sample application can be built and run.

### 4.1 D2XX Linux Driver installation for Raspberry Pi

Download [D2XX Linux ARM](#) driver ([Suitable for Raspberry Pi version 1.1.12 in this application](#) note)

```
tar xvf libftd2xx1.1.12.tar.gz (decompress the D2XX driver)
```

```
su (switch to root user)
```

```
cd /release/build/arm926
```

```
cp libftd2xx.so.1.1.12 /usr/local/lib
```

```
ln -sf /usr/local/lib/libftd2xx.so.1.1.12 /usr/local/lib/libftd2xx.so (Creates a symbolic link to the shared object)
```

### 4.2 Run the FT800 Raspberry Sample Code

Download the FT800 Raspberry Pi sample code ([FT800Rpi.tar.gz](#))

```
tar xvf FT800Rpi.tar.gz
```

```
cd /FT800 Raspberry Pi/Build/Linux/
```

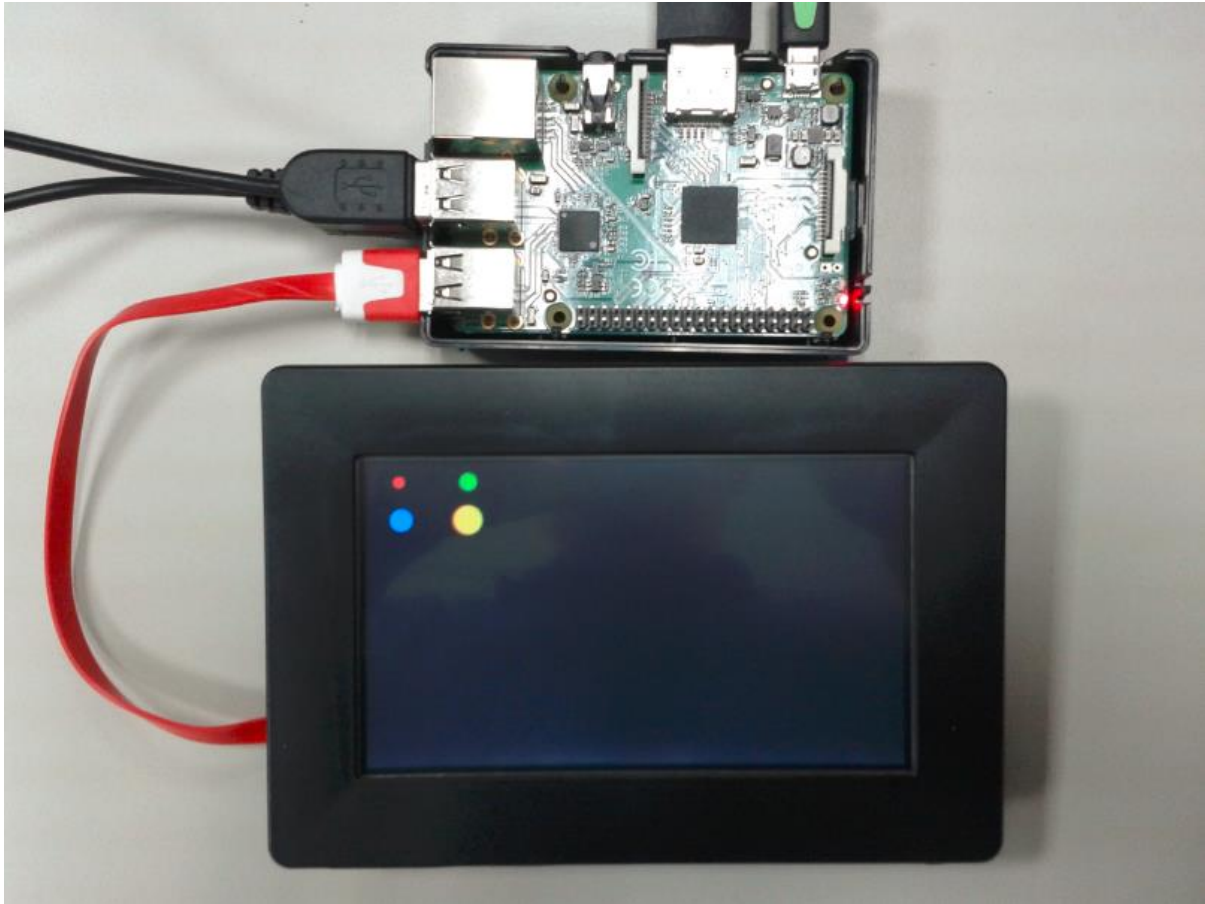
```
make
```

```
rmmod ftdi_sio (remove VCP driver)
```

```
LD_LIBRARY_PATH=/usr/local/lib ./FT800Rpi (run the application)
```

## 5 Test Results

The image below shows the display produced by the sample code. The resulting display is the same as that shown in section 2.5.3 of the [FT800 Programmers Guide](#).



**Figure 5.1 Test image displayed on screen**



## 6 Conclusion

This application note has demonstrated the way in which a Single Board Computer can be interfaced to the FT800. There are many cases where a Single Board Computer may be used within a product and may require a small display with the possibility of touch and sound functionality, and the FT800 provides a good solution for this.

The example uses the Raspberry Pi due to its wide availability and range of resources. The OS images are available from the Raspberry Pi website and debugging can be carried out without additional JTAG interfaces etc. using the monitor attached to the Raspberry Pi. However, the FT800 can be interfaced to many other Single Board Computers.

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## Appendix A – References

### Document References

[EVE Product Page](#)

[FT800 Datasheet](#)

[FT800 Programmers Guide](#)

[VM800BU Datasheet](#)

[AN\\_240 EVE From the Ground Up](#)

[EVE SampleApp](#)

[Raspberry Pi Download](#)

[Project source code](#)

### Acronyms and Abbreviations

Terms	Description
PIDORA	Pidora is a Fedora Remix optimized for the Raspberry Pi computer.
SBC	A single-board computer (SBC) is a complete computer built on a single circuit board.
SPI	Serial Peripheral Interface
TF Card	A TF card stands for a Trans Flash card.
USB	Universal Serial Bus

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## Appendix C – Revision History

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Revision	Changes	Date
1.0	Initial release	2015-02-09
1.1	Updated the broken link in Section 1 Introduction	2015-11-17