



# Application Note

## AN\_296

# FT800 Example with Arduino Over I2C

**Version 1.0**

**Issue Date: 2014-03-04**

The FTDI FT800 video controller offers a low cost solution for embedded graphics requirements. In addition to the graphics, resistive touch inputs and an audio output provide a complete human machine interface to the outside world.

This application note will provide a simple example of developing Arduino Sketch code to control the FT800 over I<sup>2</sup>C. The principles demonstrated can then be used to produce more complex applications.

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## 1 Introduction

The FT800 operates as an SPI or I<sup>2</sup>C peripheral to a main system processor providing a low-cost, yet complete, human interface experience by the incorporation of graphics rendering, touch screen sensing and audio capabilities. It is controlled over a low-bandwidth SPI or I<sup>2</sup>C interface allowing practically any microcontroller to be used.

For this application, an Arduino board is coupled with the MikroElektronika EVE Click board FT800 module and the Arduino Sketch development environment. The target application demonstrates the use of the standard Arduino libraries to initialize and display different elements on the LCD of the VM800C. The design flow follows concepts introduced in application note [AN\\_240 FT800 From the Ground Up](#).

Once these concepts are mastered, this example can be used as a basis for larger and more complex applications that the FT800 has to offer: graphics primitives (e.g. lines, shapes, text), inbuilt widgets (e.g. sliders, switches, dials), touch events and audio output.

Note: It is recommended to view the code while reading this application note.

**DISPLAY****AUDIO****TOUCH**

## 2 Software Architecture

This project consists of two files:

- FT800.h – a header file containing all of the FT800-specific values for memory locations, command values, etc.
- AN\_296.ino – the main program file

An “abstraction layer” concept was explicitly avoided in this example. Rather, direct use of the Arduino libraries demonstrates the simplicity of sending and receiving data through the FT800 while producing a graphic output.

Source code for the Arduino Sketch used in this application note can be found here:

[http://www.ftdichip.com/Support/SoftwareExamples/EVE/AN\\_296.zip](http://www.ftdichip.com/Support/SoftwareExamples/EVE/AN_296.zip)

### 2.1 FT800.h

This header file contains all of the information that is specific to the FT800 and assigns meaningful names to each value or address. The file is separated into the following sections:

- Memory Map – base addresses of the sections of memory within the FT800
  - RAM\_CMD = 4KB ring buffer to place Co-Processor commands
  - RAM\_DL = 8KB buffer to place display lists
  - RAM\_G = 256KB general element memory for images, fonts and audio data
  - RAM\_PAL = 1KB color palette
  - RAM\_REG = FT800 registers
- Register Addresses
  - Each of the FT800 registers is named and associated with its address. Refer to the [FT800 Datasheet](#) for register sizes.
- Graphic Engine Commands
  - Each command associated with the FT800 graphics engine is assigned a value according to the [FT800 Programmers Guide](#). Many of the Co-Processor commands require additional arguments.
- Display List Commands
  - Each display list command is assigned a value according to the FT800 Programmers Guide. All display list commands are 4-bytes in length. The first byte is the actual command. The remaining three bytes contain the necessary arguments.
- Command and register value options
  - Assorted named values useful for the main program.
- Useful Macros
  - Assorted macros to perform basic calculations.

### 2.2 AN\_296.ino

This is the main Arduino Sketch program file. In addition to standard C-language, the following standard Arduino libraries are used:

- **Arduino** – This is the base Arduino functionality.
- **Serial** – Serial is used to send debug messages to the UART monitor port within the Arduino environment. Serial is integral to Arduino and does not require a separate header reference. The Serial port is configured for 9600bps, no parity, 8 data bits, one stop bit and no handshake. Use of the serial port is not required, though it may be handy for debug.
- **Digital** – GPIO pins are defined for FT800 reset (PD#) and Interrupt (INT# - not used in this example). Digital is integral to Arduino and does not require a separate header reference.
- **Wire** – The Wire library is used to provide the actual clocked data into and out of the FT800 following the I<sup>2</sup>C protocol. The default rate of 100Kbps is used. Many Arduino boards can support at least 400Kbps with sufficient pull-ups on the SCL and SDS signals. The FT800 will support up to 3.4Mbps over I<sup>2</sup>C.

## 3 User Application

The intent of the user application is to render a circle on the LCD. The initial circle is white, then each time through the loop, the color toggles between red and white. Touch and audio are not covered.

### 3.1 FT800 Graphics Rendering

There are two methods available for rendering graphics elements, playing audio and sensing touch events.

- The first way is to write display list commands directly to the RAM\_DL (Display List RAM).  
*Note: This method is illustrated when blanking the screen as part of the initialization of the FT800.*
- The second way is to write a series of Co-Processor commands or display list commands to the RAM\_CMD (Command FIFO). The Co-Processor then creates the display list in RAM\_DL based on the commands which it is given in the RAM\_CMD FIFO. This method makes it easier to combine the drawing of graphics objects (lines etc.) and Widgets (slider etc.) on the same screen.  
*Note: This method is illustrated when creating the main screen.*

Although it is in theory possible to mix both methods when creating a new display list (screen) it is recommended that only one of the two methods is used in any given screen. This is because the RAM\_DL would be written by both the MCU and the Co-Processor within the FT800.

#### 3.1.1 Display List

With the Display List, the FT800 can draw several primitives (points, lines, edge and line strips, rectangles and images), manipulate the screen LCD parameters, read and write registers, etc. It can also play synthesized sounds and audio files and work with the raw touch screen activity (X-Y coordinates, touch pressure).

There is an 8K Display List buffer. All display list commands are 4-bytes in length, allowing for up to 2K commands. A display list command is constructed by logically combining the command byte with the necessary parameters. For example, this application uses the POINTS primitive. A BEGIN command is used coupled with the type of object associated with following commands - in this case, POINTS. The value for BEGIN is 0x1F, located in bits 31 through 24 of the command. Bits 23 through 4 are not used (reserved). Bits 3 through 0 indicate the primitive type. POINTS is type 2. The full command is then 0x1F000002.

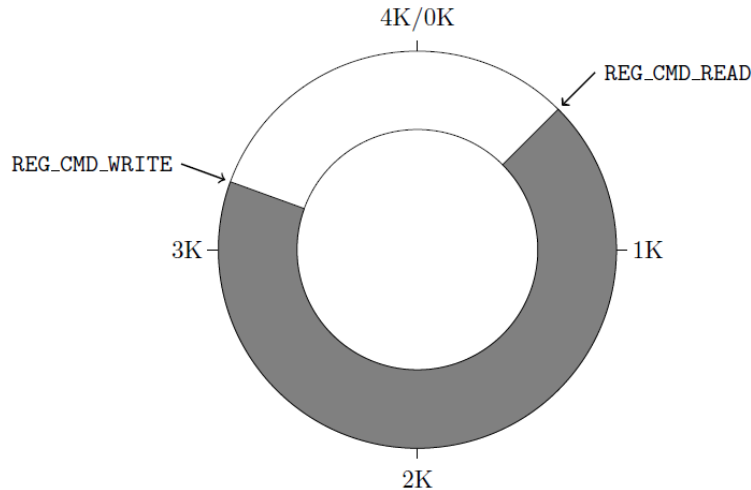
Each display list command is constructed in a similar fashion. When sending these values to the FT800, they are sent in "little-endian" format, or least significant byte first: 0x02, 0x00, 0x00, 0x1F.

Commands are sent to successive locations in the RAM\_DL (0x100000) memory of the FT800. The last Display List command of every list is "DISPLAY" to instruct the FT800 to process the commands and draw the screen. Processing is started when the register REG\_DLSWAP is written with a value of 1 (swap after the current line) or 2 (swap after the current screen).

At this point, the list made "active", and a new list can now be written starting at RAM\_DL again.

### 3.1.2 Co-Processor

While the Display List covers basic screen manipulation, the Co-Processor allows more advanced rendering using inbuilt widgets, memory management and touch tags. The command memory for the Co-Processor is located at RAM\_CMD (0x108000). While the display list always starts at the beginning of RAM\_DL, the Co-Processor uses a 4K FIFO ring buffer.



Note: This FIFO is mapped at FT800 memory addresses 108000h (RAM\_CMD) to 108FFFh (RAM\_CMD + 4095)

**Figure 3.1 - Co-Processor Ring Buffer**

The index of the last command executed is held in the register REG\_CMD\_READ, while the index of the last command written is in REG\_CMD\_WRITE. The process for adding commands is:

- 1) Read REG\_CMD\_READ and REG\_CMD\_WRITE. Loop here until they're equal.
- 2) Write new commands starting at REG\_CMD\_WRITE.
- 3) Update REG\_CMD\_WRITE with the next address following the last command in the list (4-byte aligned).
- 4) With the new value in REG\_CMD\_WRITE, the Co-Processor will start executing each command and updating REG\_CMD\_READ until it reaches REG\_CMD\_WRITE.

While only one type of rendering is recommended; display list commands can be embedded into the command list. This allows mixing of the primitive graphics elements with widgets allowing the full capabilities of the FT800 to be utilized. The loop() function utilizes this method of embedding display list commands into the command list.

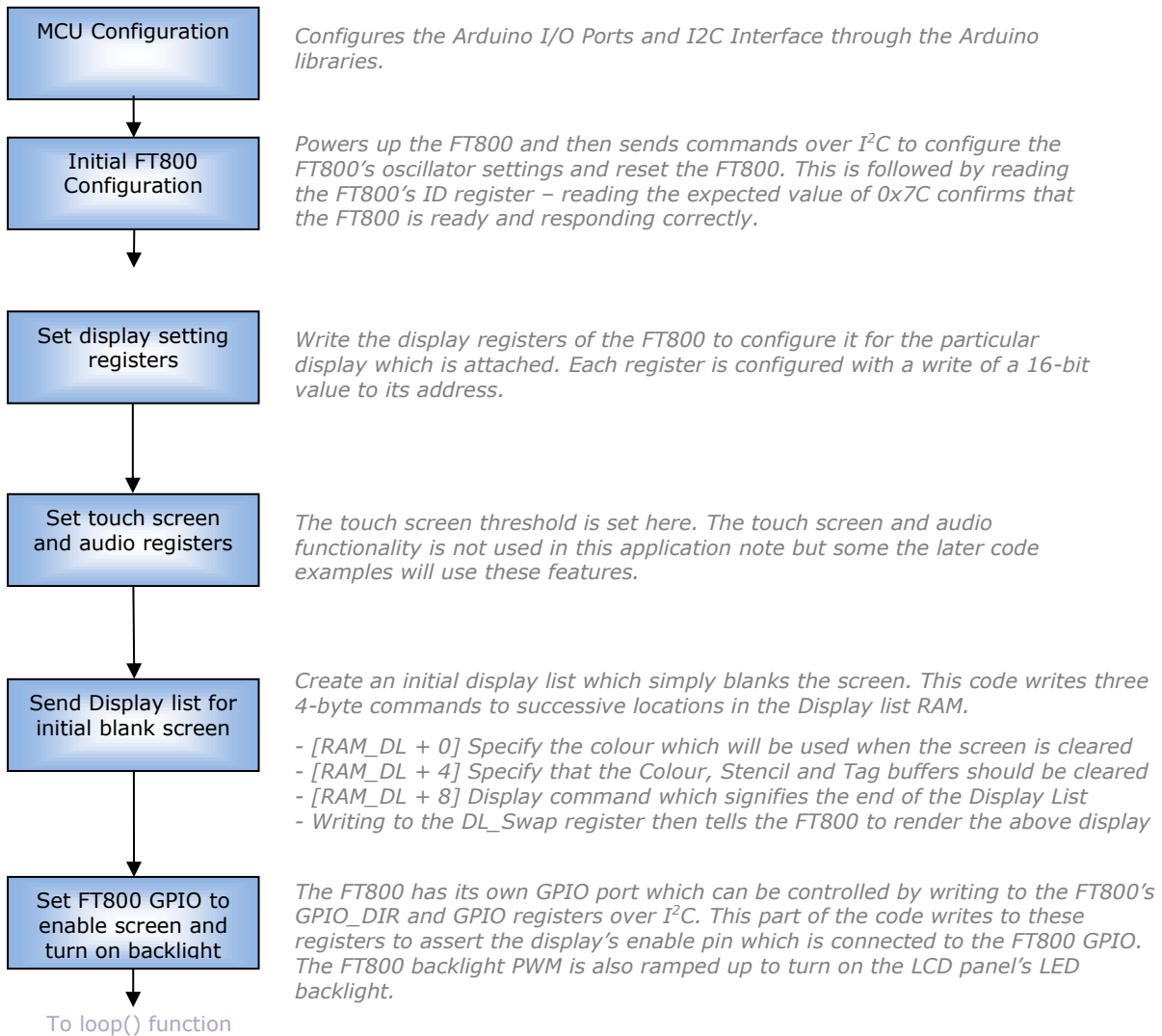
## 3.2 Arduino Sketch

A standard Arduino Sketch application consists of two standard functions: setup() and loop().

- void **setup**(void)
  - This code is executed once after reset of the Arduino.
- void **loop**(void)
  - This code is continually executed after setup() completes.

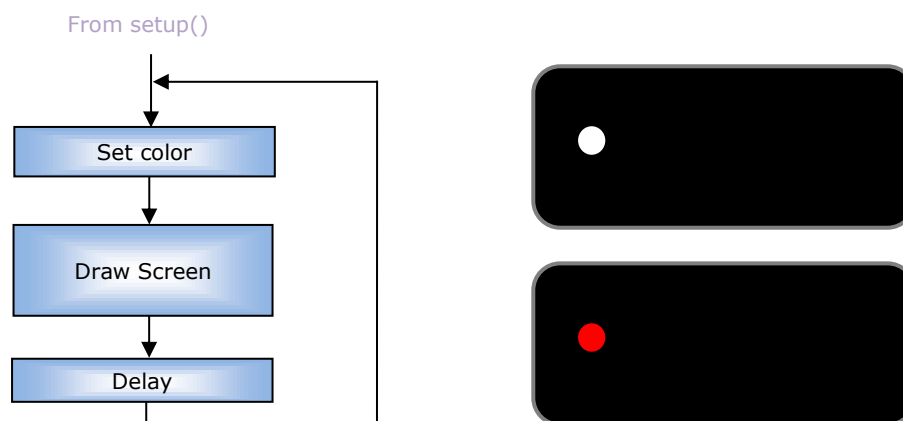
### 3.2.1 setup()

All FT800 and Arduino initialization and configuration requirements are handled in setup():



### 3.2.2 loop()

The generated images are shown while executing loop().



**Figure 3.2 - Sketch Program Output**

The Draw Screen block above performs the following steps:

1. Check the Co-Processor command buffer pointers. Wait until they're equal.
2. Alternate active colors between white and red (start with white).
3. Start the display list.
4. Clear the screen to black to eliminate any artifacts from the previous screen.
5. Clear the color, stencil and tag buffers.
6. Set the active color.
7. Define a point location and size.
8. Display the screen.
9. Swap display lists.

### 3.2.3 Other functions

Several functions provide basic read and write capabilities for accessing the FT800:

- void **ft800memWrite8**(unsigned long ftAddress, unsigned char ftData8)
- void **ft800memWrite16**(unsigned long ftAddress, unsigned int ftData16)
- void **ft800memWrite32**(unsigned long ftAddress, unsigned long ftData32)
  - This function writes a value from the Arduino through the I<sup>2</sup>C port to the FT800.
  - Available in three "sizes": 8-bits (unsigned char), 16-bits (unsigned int) and 32-bits (unsigned long).
  - The sequence of events is:
    - Send the I<sup>2</sup>C Start condition
    - Send the MEM\_WRITE command combined with the 3-byte address
    - Send the data, least significant byte first
    - Send the I<sup>2</sup>C Stop condition
- unsigned char **ft800memRead8**(ftAddress)
- unsigned int **ft800memRead16**(ftAddress)
- unsigned long **ft800memRead32**(ftAddress)
  - This function reads a value from the FT800 through the I<sup>2</sup>C port to the Arduino.
  - Available in three "sizes": 8-bits (unsigned char), 16-bits (unsigned int) and 32-bits (unsigned long).
  - The sequence of events is:
    - Send the I<sup>2</sup>C Start condition
    - Send the MEM\_READ command combined with the 3-byte address
    - Send the I<sup>2</sup>C Restart condition
    - Read the data, least significant byte first and construct the return value
    - Send the I<sup>2</sup>C Stop condition
    - Return the read data
- void **ft800cmdWrite**(unsigned char ftCommand)
  - This function sends specific commands from the Arduino through the I<sup>2</sup>C port to the FT800.
  - A command is one of 8 3-byte values as noted in section 4 of the FT800 Datasheet. Since the second and third bytes are always zero, an 8-bit value is passed to the function.
  - The sequence of events is:
    - Send the I<sup>2</sup>C Start condition
    - Send the command byte
    - Send two bytes with the value 0x00
    - Send the I<sup>2</sup>C Stop condition
- void **incCMDOffset**(unsigned int currentOffset, unsigned char commandSize)
  - This function ensures the command offset of the graphics processor command buffer rolls over within the 4KB ring buffer size.



## 4 Hardware

For this example, the MikroElektronika EVE Click board was used in conjunction with an Arduino Pro. The EVE click board has an LED on the pin used for the I2C Address bit A2, effectively pulling it to zero. The other two I2C address pins are not connected and internally pulled high by the FT800. The I2C base address for this connection is 0 0 1 0 A2 A1 A0, or 0x23.

**Note:** The VM800C and VM800B kits only support SPI operation. I2C is not available since the MODE pin of the FT800 is connected directly to ground.

Any currently available Arduino can be used to interface with the FT800. The code has been tested with the Arduino Pro.

This application uses compiler directives to select the platform type and LCD size.

```
// Set LCD display resolution here
//#define LCD_QVGA // QVGA = 320 x 240 (VM800B/C 3.5")
#define LCD_WQVGA // WQVGA = 480 x 272 (VM800B/C 4.3" and 5.0")

// Set Arduino platform here
//#define VM800B // FTDI FT800 "Plus" board with AT328P (CS# on I/O 9)
#define ARDUINO // Arduino Pro, Uno, etc. (CS# on I/O 10)
```

The connection between the Arduino board and the EVE Click board is made with five wires. 3.3V power was supplied separately to the EVE click 3.3V and GND pins since the LCD panel requires approximately 150mA:

Signal	Arduino	EVE Click
SCL	Analog 5 (SCL)	SCLK (I2C_SCL)
SDA	Analog 4 (SDA)	MISO (I2C_SDA)
I2C_A0	none	MOSI (I2C_A0) n/c Internally pulled high by FT800
I2C_A1	none	CS# (I2C_A1) n/c Internally pulled high by FT800
I2C_A2	none	Pulled low on EVE Click board
INT#	Digital 3	INT#
PD#	Digital 2	PD#
Ground	GND	GND

**Table 4.1 - Pin Connections**

## 5 Conclusion

This application note presented a simple example utilizing an Arduino platform with the standard Sketch IDE and libraries to initialize the FT800. This was followed by the creation of different displays using the graphics processor commands. Low-level I<sup>2</sup>C function calls were created to allow convenient methods of sending and receiving data to the FT800.

Other display screens that contain other graphics objects, images and widgets, as well as audio output and touch events can be implemented through changing the code within the Arduino loop() function.

The I<sup>2</sup>C transfer calls could also be expanded to include more complex, multi-byte transfers useful for image and audio file transfers to and from the FT800 memory. Interrupts can also be enabled to indicate touch events, completion of display lists, etc. Any Arduino-compatible circuit can be used.

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## Appendix A – References

### Document References

[EVE Product Page](#)

[FT800 Datasheet](#)

[FT800 Programmers Guide](#)

[VM800C Datasheet – Credit Card sized development board with FT800](#)

[VM800B Datasheet – Bezel-mounted Display with FT800](#)

[AN\\_240 EVE From the Ground Up](#)

[AN\\_259 FT800 Example with 8-bit MCU](#)

[Arduino Sketch IDE](#)

[Arduino Sketch Language Reference](#)

[Arduino Hardware](#)

[Project source code](#)

### Acronyms and Abbreviations

Terms	Description
CS#	Chip Select
GND	Ground
HMI	Human-Machine Interface
I <sup>2</sup> C	Inter-Integrated Circuit
INT#	Interrupt
LCD	Liquid Crystal Display
MISO	Master In / Slave Out
MOSI	Master Out / Slave In
PD#	Power Down
SCLK	Synchronous Clock
SPI	Synchronous Peripheral Interface

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## Appendix C – Revision History

Document Title: AN\_296 FT800 Example with Arduino Over I2C  
Document Reference No.: FT\_000980  
Clearance No.: FTDI# 372  
Product Page: <http://www.ftdichip.com/EVE.htm>  
Document Feedback: [Send Feedback](#)

Revision	Changes	Date
1.0	Initial Release	<b>04/03/14</b>